Programming the KW45 flash for Application and Radio firmware via Serial Wire Debug during mass production

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**Application note** 

#### **Document information**

Information	Content		
Keywords AN14003, KW45 processor, KW45B41Z board, fuse programming, burning CM33 ar firmware, mass production, keys preparation, debug authentication, J-Link, Secure F Software Development Kit (SPSDK)			
Abstract	This application note describes an efficient method to merge programming the KW45 fuse, burning CM33 and NBU firmware operations into one binary file during mass production. It also describes a method for debug authentication.		



## 1 Introduction

KW45 is a three-core platform that integrates a Cortex-M33 application core (CM33), a dedicated Cortex-M3 radio core, and an isolated EdgeLock Secure Enclave. The radio core, also called as Narrow Band Unit (NBU) features a Bluetooth Low Energy (LE) unit with a dedicated flash. The memories integrated in the NBU consist of Bluetooth LE controller stack and radio drivers.

On KW45, only boot ROM has access to the NBU flash. The ROM bootloader provides an in-system programming (ISP) utility that operates over a serial connection on the microcontroller units (MCUs).

The speed of programming the image using ISP is relatively slower than SWD. During the mass production of KW45, it is necessary to program the fuse first, download the NBU firmware and finally download the CM33 firmware. This document describes a method, which merges the fuse programming and burning CM33 and NBU firmware operations to produce a single binary file. The method increases the production efficiency as it requires downloading the merged binary file only once through Serial Wire Debug (SWD). The document also describes a method to write the RoTKTH and SB3KDK fuse keys to a KW45B41Z board in which these keys are null.



**Note:** The method of burning the fuse provided in this document cannot be reversed. The keys programmed to fuses on KW45 cannot be changed anymore. Therefore, it is recommended to modify the fuse with caution.

## 2 Prerequisites

A basic understanding of the boot process of ROM boot and security is required for implementing the steps described in this document. For more details, refer to the *KW45 Reference Manual*, see <u>Section 8 "References"</u>.

In brief, the process implements fuse programming and updates NBU in the CM33 image. Then the CM33 image and NBU image are merged to a single image. After downloading the merged image to KW45 flash of CM33 via SWD, fuse programming is done first and then the image is burnt to NBU. The flow is shown in <u>Section 2 "Prerequisites"</u>.



There are two limitations for the method:

- The flash size of the CM33 core must be large enough to store the application and the .sb3 file.
- The lifecycle of the KW45 device must be in the OEM-OPEN state.

## 3 Debug session initiation

The method to initiate a debug session varies depending on the device state and intended debug scenario.

- For a lifecycle that does not require debug authentication, the debug session can be initiated without performing debug authentication.
- For a lifecycle that requires debug authentication, debug session can be initiated only after debug authentication.

## 4 Preparing OEM keys and certificate using SPSDK

This section describes the steps for preparing OEM keys and certificate preparation using the SPSDK tool.

### 4.1 Setting up the SPSDK environment

Secure Provisioning SDK (SPSDK) is an open source python SDK library with its source code released on <u>Github</u> and <u>PyPI</u>. It provides a set of API modules for custom production tool development requiring more advanced secure provisioning flow. This document uses a Windows system as an example.

For more details, refer to SPSDK user guide on: https://spsdk.readthedocs.io/en/latest/index.html.

- 1. Install Python 3.7+ on a personal laptop.
- 2. Open the command prompt (cmd.exe). Then, run the following commands to install SPSDK:

```
python -m venv venv
venv\Scripts\activate
python -m pip install --upgrade pip
pip install spsdk
```

- 3. The above commands create a virtual environment on the user's laptop. Then install SPSDK also includes dependence file on the virtual environment.
- 4. Jupyter Lab is a web-based interactive development environment. NXP provides examples based on Jupyter Notebook as an easy interactive tool for user, on above virtual environment install Jupyter Lab by using the command:

pip install jupyterlab

Jupyter Notebook examples are also provided as interactive documentation. For users with no experience with the Jupyter environment, reading the tutorial available at the below URL is recommended: <a href="https://docs.jupyter.org/en/latest/start/index.html">https://docs.jupyter.org/en/latest/start/index.html</a>

- 5. KW45 Jupyter notebook example file is located in path where SPSDK is released on Github.
  - This path is: spsdk/<u>examples</u>/jupyter\_examples/kw45xx\_k32w1xx/
  - The file extension is . ipynb, download it to personal laptop.
- 6. In the virtual environment, launch the Jupyter Lab using the command below:

cd C:\path of store Jupyter notebook example.ipynb
jupyter-lab

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# AN14003

Programming the KW45 flash for Application and Radio firmware via Serial Wire Debug during mass production



Each section of Jupyter Notebook example contains an executable field and descriptions. To execute a field, select it and then click the **Execute** button in the top menu icon of the window. Refer Figure 3.

### 4.2 Preparing the keys and certificate

Two types of keys must be written to KW45 fuse during mass production. In a factory chip, the keys in the fuse are null. These keys are listed below:

- RoTKTH (CUST PROD OEMFW AUTH PUK): Four Roots of Trust Key pairs (RoTK) generate this key.
- SB3KDK (CUST\_PROD\_OEMFW\_ENC\_SK): It is an Advanced Encryption Standard (AES) key.

### CAUTION:

The fuse is a program-once region. If the RoTKTH and SB3KDK keys are not written to the fuse or the incorrect keys are written to the firmware, then the method described in this document would fail.

By default, RoTKTH and SB3KDK are provided for KW45B41Z-EVK board. This document describes a method to write these default keys to a KW45B41Z board in which these keys in fuse are null. For more details on how RoTKTH and SB3KDK keys can be generated and how they are used for secure boot, refer to the Application Note '*Secure Boot for KW45 and K32W* (*AN13838*). See <u>Section 8 "References"</u>.

To execute the code to generate new keys, follow the description in the Jupyter Notebook example. Users can change the WORKSPACE as per the actual keys and certificate file storage path, set VERBOSITY as '-v' to observe the debug and additional information. Refer to Figure 4.

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## AN14003

# Programming the KW45 flash for Application and Radio firmware via Serial Wire Debug during mass production

Ŧ	Keys preparation					
	First we need to generate RoTKs (Root of Trust Keys) and optionally ISK (Image Signing Certificate). We will use <i>nxpcrypto</i> app for this purpose. Script by default generates 4 RoTKs and 1 ISK key (full set of possible keys). Feel free to modify it according your needs. RoTK 0 generation is mandatory.					
	See the script's comments and modify the script according to the application security requirements. Key generation is done only once on keys, RoTKTH value is calculated and loaded in the device fuses so that's why keys cannot be changed anymore for the device.	in the beginning. Based on generated				
[1]:	%alias execute echo %1 && %1 %alias_magic ! execute					
	import os import pprint					
	<pre>pp = pprint.PrettyPrinter(indent=4)</pre>					
	WORKSPACE = "workspace/" # change this to path to your workspace VERBOSITY = "-v" # verbosity of commands, might be -v or -vv for debug or blank for no additional info					
	Created `%!` as an alias for `%execute`.					
Figure 4. Setting the workspace path and verbosity						

If you want to use existing keys and/or certificate, then execute the first executable field, skip executing the key and certificate preparation steps, and generate the SB3KDK code. Then, change the keys and certificate path as shown in <u>Section 5.1 "NBU image preparation"</u>.

The RoTKTH and SB3KDK keys can be observed during Sb3.1 generation when VERBOSITY is set to "-v" as shown in Figure 5.

	SB3.1 generation	
[8]:	We have created certificates and keys required for the creation of SB3.1 file. Let's create a SB3.1.	
	<pre>B]: %! nxpimage \$VERBOSITY sb31 export \$SB31_TEMPLATE_PATH assert _exit_code == 0 assert os.path.exists(WORKSPACE+SB31_FILE_PATH)</pre>	
	nxpimage -v sb31 export workspace/sb31_config.yml Success. (Secure binary 3.1: C:/jia/kw45 jupyter notebook/workspace/sb3.sb3 created.)	
	INF0:spsdk.sbfile.sb31.images:SB3KDK: 3cb97b3013ac513cf183e5f9fdce699d489caf7fad203b613d0fef8e55eff775 INF0:spsdk.utils.crypto.cert_blocks:RoTKTH: f4c503ee4c765debe293410b551c7e08bca5c226b3a61afcee6ae92b70db895c2d922cfbad	e15b654d55645b751780c
_		

#### Figure 5. Observing keys

### 5 Mass processing and image preparation

### 5.1 NBU image preparation

NBU firmware file (.xip) is provided in the SDK path:

SDK store path\middleware\wireless\ble controller\bin\

**Note:** If the user burns the fuse using EVK default keys, the .sb3 file located in the above path can be used. Otherwise, the user must first generate the .sb3 file for the customer using the .xip file.

#### 5.1.1 SB3 file generation

An Sb3 file can be generated by executing the "*Prepare SB3.1 configuration file*" code in the Jupyter Notebook example. For this purpose, provide the following in the fields:

- The path of the keys (SB3KDK KEY PATH, ROTKO PRIVATE KEY PATH)
- The certificate path (ROOT\_0\_CERT\_PATH, ROOT\_1\_CERT\_PATH, ROOT\_2\_CERT\_PATH, ROOT\_3\_CERT\_PATH) The path is defined and filled to the above parameters if the user executes all executable fields on the Jupyter notebook example.

To use the existing keys and/or certificate, you must define the path of existing keys and/or certificate in the above parameters as shown in Figure 6.



### 5.1.2 Changing the lifecycle (optional)

The KW45 lifecycle can be changed by adding a programFuse command in the SB3 file generation code (refer to Figure 7). However, If you do not want to change the lifecycle, then do not add this command.



Figure 7. Program Fuse command

Note:

- If the board lifecycle is changed to an after OEM-OPEN state (for example, ... 0x0F) by adding the programFuse command, the secure boot is enabled after update of NBU. This implies that the CM33 image must be signed by the keys generated. Refer to <u>Section 4.2 "Preparing the keys and certificate"</u> for generating keys.
- The programFuse command can be added to change the board lifecycle to any after OEM-OPEN state (for example, ... 0x0F). In such a case, the flash of CM33 cannot be accessed via SWD, unless debug authentication is enabled by using the steps mentioned in <u>Section 6 "Debug authentication"</u>.

### 5.2 CM33 image preparation

Take the SDK project <code>otac\_att</code> as example, set the <code>gEraseNVMLink\_d</code> linker symbol to 0 while generating the binary file.

If the flash of NBU is empty, the Bluetooth Low Energy example code is stacked when initializing NBU. Also an issue would occur when the Bluetooth Low Energy host stack is initialized. So, use a flag stored in a non-volatile memory to indicate whether to perform the normal Bluetooth Low Energy process, or perform burn NBU image process. For the process described in this document, this flag stores a reserve variable in HWParameters as shown in Figure 8.

51	-	#endit
52		
53	_	<pre>static void start_task(void *argument)</pre>
54	보	
~ 55	닌	#11 TEST_UPDATE_NBU_FROM_APP_IN_SECURE_LIFECYCLE
56	Д	uint32_t status;
57	뉘	/* Load the HW parameters from Flash to KAN
58		Ins demo test if NBU can update from Hiss app when in mass production:
59		1. Download MSS signed firmware(xip file) and NBO with .sbS format to
61		) lie a perconal defined flag in HuDargmeters check whether hupp NBU
62		2. Ose a personal capital judg an invaluncers check michael bain indo. Refore start RLF nlatform check if i needs undate NRLI if ves
63		Bergarse there have no NBU formance when first download so BLF
64		platform is not started before NBU firmware is burned */
65		status = NV ReadHWParameters(&pTestHWParams):
66		
67		if((status == 0U) && pTestHWParams->reserved[63] != 0xFF)
68	白	
69	H	#endif
70		
71		/* Start BLE Platform related ressources such as clocks, Link layer and HCI transport to Link Layer */
72		<pre>(void)APP_InitBle();</pre>
73	$\bot$	
~ 74	닉	#if TEST_UPDATE_NBU_FROM_APP_IN_SECURE_LIFECYCLE
75	F	1
/6	FI	
70		APD TeleSonvices (timers, serial manager, low power, lea, button, etc) 7
70		AFF_INITSERVICES();
80		/* Start Hast starb */
81		Bluetooth/EHost AppTnit():
82		
83		while(TRUE)
84	白	
85		<pre>BluetoothLEHost HandleMessages();</pre>
86	+	}
87	L	}
88		
Eim		9 Running NRU flag
rigi	ur	

### 5.2.1 Default OEM keys on KW45B41Z board

For the KW45B41Z-EVK board, NXP provides the default keys in fuse and these are shown in <u>Figure 9</u>. However, for the KW45 chip received from the factory, by default, the SBKDK and RoTKTH keys in the fuse are null. Therefore, writing these two keys to fuse is essential. Otherwise, the sb3 update would fail.

```
#if TEST_UPDATE_NBU_FROM_APP_IN_SECURE_LIFECYCLE
extern hardwareParameters_t *pTestHWParams;
nboot_context_t JiaTestContext;
/*fill user SB3KDK and RoTKTH in below array, in this demo, it use same key as in KW45 EVK */
uint8_t user_SB3KDK[32] = {0x7a, 0xa7, 0xef, 0x98, 0x13, 0xb3, 0x56, 0x12, 0x57, 0xb8, 0x83, 0x7d, 0xab, 0x26, 0x22, 0x53,
0x01, 0xdf, 0x35, 0x11, 0x21, 0x7f, 0x27, 0x33, 0xc7, 0x1d, 0xad, 0xcd, 0x44, 0x77, 0x22, 0xd1};
uint8_t user_RoTKTH[32] = {0x65, 0x0d, 0x80, 0x97, 0x07, 0x9f, 0xf2, 0x7a, 0x3e, 0x8a, 0x2d, 0xa1, 0x47, 0x81, 0xb9, 0x22,
0xfd, 0x82, 0x95, 0xb6, 0xc0, 0x0b, 0xfa, 0x06, 0x7f, 0x00, 0xe8, 0x7f, 0x1a, 0x16, 0xb8, 0xb3};
#endif
Figure 9. Default keys on KW45B41Z-EVK board
```

#### 5.2.2 Writing OEM keys in application code by nboot API

The KW45 ROM bootloader provides the nboot API that can program the fuse. Follow the below steps to enable the nboot API:

- 1. In the BLE example project, add the driver files fsl romapi.c and fsl nboot.h to the project.
- 2. Open the file fsl\_romapi.c and remove the API related to the flash operation. This step is required to prevent duplicate definitions error that might appear while compiling the project.
- 3. In otap\_client\_att.c, add:

#include "fsl nboot.h"

Then, define the SB3KDK and RoTKTH array as shown in <u>Figure 9</u>. The function code shown below shows how to program the SBKDK and RoTKTH to the fuse:

```
int JiaTest Set LifeCycleAndKeys Secure(uint8 t * pSB3KDK, uint8 t * pRoTKTH)
{
    static spc_active_mode_sys_ldo_option_t SysLdoOption;
    status_t TestSta;
    uint32 t RegPrimask;
    uint8 t TestTempBuff[32] = {0};
    nboot status t TestSta1, TestSta2, TestSta3, TestSta4;
    PRINTF("\r\n------ Test read and wirte fuse -----\r\n");
    /* When select System LDO voltage level to Over Drive voltage, The HVD of System
LDO must be disabled. */
    SPC EnableActiveModeSystemHighVoltageDetect(SPC0, false);
    while(SPC GetBusyStatusFlag(SPC0)); //wait here for a while, to let HW complete
 operation
    PRINTF("\r\nSet SYS LDO VDD Regulator regulate to Over Drive Voltage(2.5V)\r\n");
    /* Set SYS LDO VDD Regulator regulate to Over Drive Voltage(2.5V) */
    SysLdoOption.SysLDOVoltage = kSPC_SysLDO_OverDriveVoltage;
    SysLdoOption.SysLDODriveStrength = kSPC SysLDO NormalDriveStrength;
     // SPC use default configuration, so we just set sys Ldo option
    TestSta = SPC SetActiveModeSystemLDORegulatorConfig(SPC0, &SysLdoOption);
    OSA TimeDelay(10); //just delay to let volitage reach the target level
    if(kStatus Success == TestSta)
    {
         /* Disabling the interrupts before making any ROM API call is suggested,
           since API code does not deal with interrupts */
        RegPrimask = DisableGlobalIRQ();
        /* Set/read keys in fuse */
        TestSta1 = NBOOT_ContextInit(&TestContextForWriteLC);
TestSta2 = NBOOT_FuseProgram(&TestContextForWriteLC,
NBOOT FUSEID CUST PROD OEMFW AUTH PUK, (uint32 t *) pRoTKTH, 32);
        TestSta3 = NBOOT FuseRead(&TestContextForWriteLC,
NBOOT_FUSEID_CUST_PROD_OEMFW_AUTH_PUK, (uint32_t *)TestTempBuff, 32);
TestSta4 = NBOOT_FuseProgram(&TestContextForWriteLC,
NBOOT FUSEID CUST_PROD_OEMFW_ENC_SK, (uint32_t *)pSB3KDK, 32);
        NBOOT ContextFree(&TestContextForWriteLC);
        /* Enable the interrupts after rom api calls */
        EnableGlobalIRQ(RegPrimask);
        /* Set SYS LDO VDD Regulator regulate to Normal Voltage(1.8V) */
        SysLdoOption.SysLDOVoltage = kSPC_SysLDO_NormalVoltage;
SysLdoOption.SysLDODriveStrength = kSPC_SysLDO_NormalDriveStrength;
        TestSta = SPC SetActiveModeSystemLDORegulatorConfig(SPC0, &SysLdoOption);
        OSA_TimeDelay(10); //just delay to let volitage reach the target level
```

Programming the KW45 flash for Application and Radio firmware via Serial Wire Debug during mass production

```
PRINTF("\r\n Set SYS LDO VDD Regulator to Normal Voltage(1.8V)\r\n");
       PRINTF("\r\nTestSta1: %X, TestSta2: %X, TestSta3: %X, TestSta4: %X \r\n",
TestSta1, TestSta2, TestSta3, TestSta4);
       for (uint8 t i=0; i < 32; i++)
        {
           PRINTF("%X", TestTempBuff[i]);
       SPC EnableActiveModeSystemHighVoltageDetect(SPC0,true);
       while(SPC GetBusyStatusFlag(SPC0)); //wait here for a while, to let HW
complete operation
       PRINTF("\r\n----- End test -----\r\n");
    }
   else
    {
       PRINTF("\r\n Failed sta is %d \r\n", TestSta);
    }
   return 0;
#endif
```

The fuse programming steps are listed below:

- The SYS LDO VDD Regulator level must be regulated to Over Drive Voltage level (2.5 V) while trying to program the fuse. The default SYS LDO VDD Regulator level is regulated to normal voltage 1.8 V.
- The nboot API does not deal with any interrupts. Therefore, you must disable the interrupts before making any nboot API calls.
- The fuse is a program-once region. Therefore, if the key region in fuse already has some values, then fuse programming fails except for the same keys.
- After the fuse is programmed, enable the interrupts.
- The SYS LDO VDD can only operate at the overdrive voltage for a limited amount of time for the life of the chip. Therefore, after programming the fuse, set the SYS LDO VDD to normal voltage.

The program keys to fuse operation must be done prior to modifying the OTA update configurations mentioned in <u>Section 5.2.3 "Updating OTA update configurations"</u>.

### 5.2.3 Updating OTA update configurations

KW45 Boot ROM has a firmware update feature that can be used for updating both CM33 and NBU firmware. For example, it indicates and provides metadata information for update to be performed in KW45 IFR0 OTACFG page. (Refer to OTA update configuration in *KW45 RM*). The target image is the NBU image prepared as mentioned in <u>NBU image preparation</u>. The NBU image is placed in the address 0x7A000 as shown in the code below.

```
void BluetoothLEHost_AppInit(void)
{
    /*Install callback for button*/
#if (defined(gAppButtonCnt_c) && (gAppButtonCnt_c > 0))
    (void)BUTTON_InstallCallback((button_handle_t)g_buttonHandle[0],
    (button_callback_t)BleApp_HandleKeys0, NULL);
#endif
#if TEST_UPDATE_NBU_FROM_APP_IN_SECURE_LIFECYCLE
    if(pTestHWParams->reserved[62] != 0xFF)
    {
    #endif
    /* Initialize Bluetooth Host Stack */
    BluetoothLEHost_SetGenericCallback(BluetoothLEHost_GenericCallback);
    BluetoothLEHost_Init(BluetoothLEHost_Initialized);
    #if TEST_UPDATE_NBU_FROM_APP_IN_SECURE_LIFECYCLE
    }
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```

Programming the KW45 flash for Application and Radio firmware via Serial Wire Debug during mass production

```
else
    {
        int res = -1;
        int st;
        OtaLoaderInfo t loader info;
        res = PLATFORM OtaClearBootFlags();
        if(res == 0)
        {
            //OTA successful, OTA update configuration will be cleared
            PRINTF("\r\nFirmware update sucessful.\r\n");
            pTestHWParams->reserved[62] = 'S';
            NV WriteHWParameters();
            PRINTF("\r\nSet HWParameter->reserved[62] as 'S' as a flag, recover
 the flag by long press button SW2\r\n");
            PRINTF("\r\nReset MCU again for running normal application\r\n");
            HAL ResetMCU();
        }
        else if (res == 1)
        {
            PRINTF("\r\nTest for update nbu firmware, NBU firmware is null,
 start nbu firmware update.\r\n");
            PRINTF("\r\nSet new image flag to IFR0 -> OTACFG\r\n");
            /* Program Keys to fuse, this must before update NBU*/
            JiaTest Set LifeCycleAndKeys Secure(user SB3KDK, user RoTKTH);
            loader info.image addr = 0x7a000;
                                                    //this is sb3 file address
that store in internal flash, align with 8Kb
                                                     //The OTA SelectedFlash-
>base offset is 0x7a000, I also use it.
            loader info.image sz = 194240;
                                                    //fill sb3 file size
            loader info.pBitMap
                                  = NULL;
            //use internal flash
            loader info.partition desc = &Test ota partition;
              loader_info.sb_arch_in_ext flash = false;
//
11
              loader info.spi baudrate
                                               = 0:
            st = PLATFORM OtaNotifyNewImageReady(&loader info);
            PRINTF("\r\nUpdate OTACFG status is %d \r\n", st);
            PRINTF("\r\nReset MCU \r\n");
            HAL ResetMCU();
        }
        else if (res == 2)
        {//OTA failed, OTA update configuration will be cleared
            PRINTF("\r\nFirmware update failed.\r\n");
        }
        else
        {//unknow OTA firmware update status
            PRINTF("\r\nUnknow firmware update status\r\n");
        }
#endif
}
```

### 5.3 CM33 signed image generation (optional)

If the device lifecycle is changed to OEM secure world closed via a command in the .sb3 file generated earlier, it signifies that after ROM boot processes the .sb3 file, the NBU image is burnt and the lifecycle is also changed. Therefore, the application image must also be signed because the secure boot feature is enabled in that lifecycle. If this step is not done, a command must be added to change the board lifecycle to an after OEM-OPEN state in the .sb3 file. In such a case, the signed image is not required.

#### Note:

The signed image feature is not provided in SPSDK for KW45 devices currently. However, the signed image can be generated by using the <u>Over The Air Programming tool</u>. Follow the steps described in Bluetooth Low Energy Demo Applications User's Guide.pdf to generate the .sb3 file. Refer to the step show in <u>Figure 10</u>. The signed image can be found in the path below:

#### tool install path\Over The Air Programming 1.0.6.4\Secured\signedcm33.bin

• Use the Keys and Certificate files generated using the steps mentioned in <u>Section 4.2 "Preparing the keys</u> <u>and certificate"</u>" for signed image generation.

s is a second seco				
Family	kw45xx			
Container Key Blob Encryption Key	.\keys_and_certs\sb3kdk.txt		Clear	Browse
Description	384_digital_key_device_freertos			
KDK Access Rights	3			
Container Configuration Word	0x0			
Firmware Version	0x0			
Root Certificate 0 File	.\keys_and_certs\ec_secp384r1_cert0.pem		Clear	Browse
Root Certificate 1 File	.\keys_and_certs\ec_secp384r1_cert1.pem		Clear	Browse
Root Certificate 2 File	.\keys_and_certs\ec_secp384r1_cert2.pem		Clear	Browse
Root Certificate 3 File	.\keys_and_certs\ec_secp384r1_cert3.pem		Clear	Browse
Main Root Certificate Id	0			
Main Root Certificate Private Key File	.\keys_and_certs\ec_pk_secp384r1_cert0.pem		Clear	Browse
Root Certificate Elliptic Curve	secp384r1			
Use ISK	true	U		
Signing Certificate File	.\keys_and_certs\ec_secp384r1_sign_cert.pem		Clear	Browse
Signing Certificate Private Key File	.\keys_and_certs\ec_pk_secp384r1_sign_cert.pem		Clear	Browse
Signing Certificate Constraint	0x0			
ISK Certificate Elliptic Curve	secp384r1			
Signing Certificate Data			Clear	Browse
Container Output File	ontainer Output File C\002.data\KW45\SDK_2_12_2_KW45B41Z-EVK\boards\kw45b41zevk\wireless_examples\bluetooth\otac_att\freertos\iar			
Commands [{ { "erase": { "address": "0x0", "size": "0x7A000" } }, { "load": { "address": "0x0", "file": ".\\signedcm33.bin" } }]		Reset	Enable	
	Γ	Copy Json Content	ОК	Cano

#### Figure 10. SB3 JSON configuration

AN14003 Application note

Programming the KW45 flash for Application and Radio firmware via Serial Wire Debug during mass production

### 5.4 Merging CM33 image and NBU image

Open the signed image file and .sb3 file using a Hex file editor tool. Copy the contents of .sb3 file to signedcm33.bin file, located in the address 0x7A000. Add a padding of 0x00 between the valid signedcm33.bin to 0x7A000 as shown in Figure 11.



After merging CM33 image and NBU image, the merged image can be burnt to KW45 via SWD for mass production.

#### **Debug authentication** 6

Debug authentication scheme is a challenge-response scheme and assures that only a debugger, which has possession of the required debug credentials can successfully authenticate over debug interface. Such a debugger can also access restricted parts of the device. The below sections describe steps for debug authentication.

### 6.1 Preparing keys and certificates for debug

Prior to generating debug credentials, it is necessary to generate an EC keypair (secp256r1 or secp384r1) for the debugger known as Debug Credential Key (DCK).

The method of generating DCK is the same as RoTKs generation in SPSDK Jupyter mentioned in Section 4.2 "Preparing the keys and certificate", shown in Figure 12. Users can use the same code and change the filename of the keypair. They can use the same syntax for generating the keypair.



Figure 12. Key pair generation

### 6.2 Debugging credentials

In the SPSDK virtual environment, use the syntax below for generating a Configuration template:

nxpdebugmbox get-template -f C:\XXXX\...\XXXX\test.yml

After successful creation, the message shown below is displayed:

The configuration template file has been created.

(venv) C:\Users\nxpdebugmbox get-template -f C:\kw45\_debug\_auth\test\test1.ym1 The configuration template file has been created.

Figure 13. Configuration template generation

Open the Configuration template file and modify the content accordingly. For details, refer to the comment mentioned in the Configuration template file.

```
socc: 0x0005
uuid: "0000000000000000000000000000000000"
cc socu: 0xFFFF
cc vu: 0
cc beacon: 0
rot meta: path of RoTKs public part, should same as keys used by .sb3
generation(e.g.. ./secp384r1 private key0.pub)
```

Programming the KW45 flash for Application and Radio firmware via Serial Wire Debug during mass production

```
rot_id: 0
dck: path of public part of the DCK(e.g. ./secp384r1_private_dck.pub)
rotk: path of RoTK private part for the rot_meta chosen by rot_id, should be the
same as keys
used by .sb3 generation (e.g. ./secp384r1_private_key0.pem)
socc: 0x0005
```

Use the syntax shown below for Debug Credential generation by using the Configuration template:

```
nxpdebugmbox -p 2.1 gendc -c C: \XXXX\...\XXXX\test1.yml C: \YYYY\...\YYYY
\test.cert1
```

where

- <XXXX> denotes the user directory path and
- <YYYY> denotes the path of test.cert1 file

```
RoT Key Hash: 650d8097079ff27a3e8a2da14781b922fd8295b6c00bfa067f00e87f1a16b8b304bf710d45cbd591e2e24be83183922c
Creating Debug credential file succeeded
```

Figure 14. Debug credential generation

### 6.3 Initiating debug authentication

1. In the virtual environment, start the NXP debug box tool by using the command:

nxpdebugmbox start

Refer Figure 15.

2. Then, select J-Link as the debug probe.

```
(venv) C:\Users\nxpdebugmbox start
    # Interface Id Description
    O PyOCD 1064975848 Segger J-Link MCU-Link
    1 Jlink 1064975848 Segger J-Link MCU-Link: 1064975848
Please choose the debug probe: 1
Start Debug Mailbox succeeded
(venv) C:\Users\
```

Figure 15. Initiating debug using the 'nxpdebugmbox start' command

3. Use the command below to initiate debug authentication (refer Figure 16):

nxpdebugmbox -v -p 2.1 -i jlink auth -b 0x0 -c C: \YYYY\...\YYYY\test.cert -k C:\ZZZZ\...\ZZZZ\secp384r1\_private\_dck.pem

C:\ZZZZ\...\ZZZZ\secp384r1\_private\_dck.pem is the private key generated using the steps described in Section 6.1 "Preparing keys and certificates for debug".

Programming the KW45 flash for Application and Radio firmware via Serial Wire Debug during mass production



Figure 16. Debug authentication

#### Starting debug

After debug authentication ends successfully, the device enables access to the debug domains permitted in the DC. Do not reset KW45, use J-Link Commander to connect to the device directly. The log is shown in Figure 17.

Programming the KW45 flash for Application and Radio firmware via Serial Wire Debug during mass production

🔜 J-Link Commander V7.84a

```
Type "connect" to establish a target connection, '?' for help
J-Link>connect
Please specify device / core. <Default>: KW45B41Z83
Type '?' for selection dialog
Device>
Please specify target interface:
  J) JTAG (Default)
S) SWD
  T) cJTAG
TIF>S
Specify target interface speed [kHz]. <Default>: 4000 kHz
Speed>
Device ″K₩45B41Z83″ selected.
Connecting to target via SWD
ConfigTargetSettings() start
ConfigTargetSettings() end
InitTarget() start
InitTarget() end
Found SW-DP with ID 0x6BA02477
DPIDR: 0x6BA02477
CoreSight SoC-400 or earlier
AP map detection skipped. Manually configured AP map found.
AP[0]: AHB-AP (IDR: Not set)
Iterating through AP map to find AHB-AP to use
AP[0]: Skipped ROMBASE read. CoreBaseAddr manually set by user
AP[0]: Core found
CPUID register: 0x410FD214. Implementer code: 0x41 (ARM)
Feature set: Mainline
Found Cortex-M33 r0p4, Little endian.
FPUnit: 8 code (BP) slots and 0 literal slots
Security extension: implemented
Secure debug: enabled
ROM table scan skipped. CoreBaseAddr manually set by user: 0x80030000
SetupTarget() start
SetupTarget() end
Memory zones:
  Zone: Default Description: Default access mode
Cortex-M33 identified.
```

#### Figure 17. Secure Debug enabled

#### Note:

Access is disabled when the KW45 device is reset. Therefore, if KW45 is reset, debug authentication must be performed again. In such a case, do not use the IDE to perform debug authentication. This is because the reset KW45 operation might be embedded in the IDE.

Programming the KW45 flash for Application and Radio firmware via Serial Wire Debug during mass production

## 7 Acronyms and abbreviations

Table 1 lists the acronyms used in this document.

Acronym	Description
AES	Advanced Encryption Standard
Bluetooth LE	Bluetooth Low Energy
DCK	Debug Credential Key
IDE	Integrated Design Environment
ISP	In-System Programming
NBU	Narrow Band Unit
OEM	Original Equipment Manufacturer
RoTKTH	Root of Trust Key Table Hash
SB3KDK	SB3 Key Derivation Key
SDK	Software Development Kit
SPSDK	Secure Provisioning SDK
SWD	Serial Wire Debug
XIP	Execute-In-Place

AN14003 Application note

## 8 References

Refer to the below documents for more information:

- Managing Lifecycles on KW45 and K32W148 (AN13931)
- Secure Boot for KW45 and K32W (AN13838)
- KW45 Reference Manual (KW45RM)
- Bluetooth Low Energy Demo Applications User's Guide.pdf. Contact your local NXP field applications engineer (FAE) or sales representative for obtaining this document.

## 9 Revision history

Table 2 summarizes the revisions to this document.

### Document revision history

Revision history				
Document ID	Release date	Description		
AN14003 v.1.1	14 June 2024	Minor updates in Section 5.2.2 "Writing OEM keys in application code by nboot API"		
AN14003 v.1.0	16 August 2023	Initial public release		

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AN14003

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Programming the KW45 flash for Application and Radio firmware via Serial Wire Debug during mass production

### Contents

1	Introduction	2
2	Prerequisites	3
3	Debug session initiation	4
4	Preparing OEM keys and certificate	
	using SPSDK	5
4.1	Setting up the SPSDK environment	5
4.2	Preparing the keys and certificate	6
5	Mass processing and image preparation	8
5.1	NBU image preparation	8
5.1.1	SB3 file generation	8
5.1.2	Changing the lifecycle (optional)	9
5.2	CM33 image preparation	10
5.2.1	Default OEM keys on KW45B41Z board	10
5.2.2	Writing OEM keys in application code by	
	nboot API	11
5.2.3	Updating OTA update configurations	12
5.3	CM33 signed image generation (optional)	14
5.4	Merging CM33 image and NBU image	15
6	Debug authentication	16
6.1	Preparing keys and certificates for debug	16
6.2	Debugging credentials	16
6.3	Initiating debug authentication	17
7	Acronyms and abbreviations	20
8	References	21
9	Revision history	22
10	Note about the source code in the	
	document	23
	Legal information	24

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