AN5384

Implementation of IEEE Standard 1149.6TM on QorlQ LS1088A Processor

Rev. 0 — 19 May 2022 Application Note

1 Introduction

This document describes how to implement the IEEE standard 1149.6 $^{^{\text{TM}}}$ on NXPs QorIQ LS1088A processor.

The IEEE standard 1149.6 fully complies with the existing IEEE standard 1149.1. Still, it also requires the following new and mandatory public JTAG instructions that are supported by the NXPs SerDes implementation on the LS1088A processor:

- EXTEST_PULSE
- EXTEST TRAIN

To provide an implementation of the IEEE standard 1149.6, NXP offers an additional custom public JTAG instruction, INIT_SETUP.

The INIT_SETUP instruction is similar, but not identical to the INITIALIZE instruction described in the *IEEE standard 1149.6*, *Annex E*. Although, here the references are made to the two of the IEEE 1149.6 mandatory instructions, EXTEST_PULSE and EXTEST_TRAIN. But, the primary focus is on the INIT_SETUP instruction.

On the LS1088A, the pins listed in Table 7 are defined as IEEE 1149.6 advanced I/O pins. All other I/O pins are defined as standard I/O and comply only with IEEE 1149.1.

Contents

1	Introduction	
2	Mandatory IEEE 1149.6 public	
	instructions	1
2.1	EXTEST_PULSE	1
2.2	EXTEST_TRAIN	2
3	INIT_SETUP instruction	3
3.1	INIT_SETUP and JTAG TAP	,
	state machine	3
3.2	JTAG opcodes	4
3.3	Test Data Register	4
3.3.1	TDR global configuration	4
3.3.2	TDR SerDes lane protocol	
	configuration	5
3.3.3	TDR SerDes reference clock	
	configuration	6
3.3.4	Full TDR layout	6
3.4	BSDL file	
4	IEEE 1149.6 compliant pins	34
4.1	Compliance pins	.35
4.2	Unsupported USB pins	.35
4.3	USB reset counter	.35
5	Revision history	. 36
Legal in	formation	

NOTE

This document is not intended to serve as an introduction to IEEE 1149.6 or its motivations. For a thorough description of testing AC coupled differential nets, see 1149.6 -2003, IEEE Standard for Boundary-Scan Testing of Advanced Digital Networks.

When USB is not in use and all USB power supplies connect to GND, the JTAG IEEE Std 1149.6 Boundary Scan Register (BSR) does not shift data between TDI and TDO. To shift USB BSR cells, power on the USB_SVDD. Here, the USB boundary cells cannot observe or control USB pins, affecting the USB BSR cells during EXTEST, EXTEST_PULSE, EXTEST_TRAIN, CLAMP, and SAMPLE. The only fails are related to USB IOs when USB_SVDD is powered on and USB_SDVDD and USB_HVDD are powered off. If all USB power supplies connect to GND, the other 1149.1 JTAG or DAP debug instructions still operate.

2 Mandatory IEEE 1149.6 public instructions

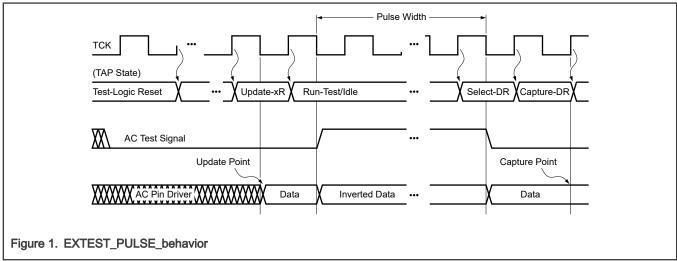
The SerDes JTAG logic on the LS1088A fully complies with the two mandatory IEEE 1149.6 instructions, EXTEST_PULSE and EXTEST_TRAIN. See 1149.6 ™-2003, IEEE Standard for Boundary-Scan Testing of Advanced Digital Networks for a thorough description of these specific instructions.

2.1 EXTEST_PULSE

According to the *IEEE 1149.6*[™]-2003, Section 5.3, EXTEST_PULSE is a mandatory instruction. It becomes effective at the falling edge of TCK in the UpdateIR TAP controller state. The Boundary Scan Register (BSR) is placed between the Test-Data Input (TDI)



and Test-Data Output (TDO) in a manner similar to the IEEE 1149.1 EXTEST instruction. The timing diagram from the official IEEE 1149.6 document is depicted in Figure 1.



A high-level description of behavior during the EXTEST_PULSE instruction is as follows:

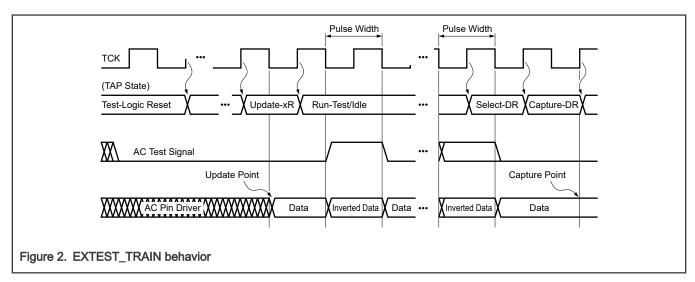
- Normal DC pins behave in the same manner as the EXTEST instruction
- Select AC Behavior for each differential SerDes TX/TX_B pin pair and enable the driver. This condition then drives the logic value in the BSR on the pin pair onto the pins at the falling edge of Test Clock (TCK) in the UpdateIR or UpdateDR states. When Run-Test/Idle is entered, the differential pin drives the inverted data signal starting at the falling edge of TCK. The differential pin drivers transition back to the original, non-inverted state at the falling edge of TCK when Run-Test/Idle state is exited, as shown in Figure 1 on the AC pin driver signals. This event generates a pulse of inverted data on a driver that is as wide as the time spent in the Run-Test/Idle TAP controller state.
- If the Run-Test/Idle TAP controller state is not entered, the output behavior of the SerDes TX pins is not distinguishable from the (DC) EXTEST instruction.
- If AC Behavior is not selected, then each differential SerDes TX/TX_B pin behaves the same as with the EXTEST instruction.
- The SerDes RX/RX_B pins are equipped with test receivers. The differential SerDes channels have one test receiver per leg.
 When either the EXTEST_PULSE or EXTEST_TRAIN instructions are in effect, it is the responsibility of the test receiver to
 reconstruct the test waveform driven by the upstream driver when either AC-coupling or DC-coupling is used. It does so by
 reacting to the edges and not the levels of the input waveform. When (DC) EXTEST is in effect, the test receiver behaves as
 a level detector.

For a thorough description of this instruction, see *1149.6*[™]-2003, IEEE Standard for Boundary-Scan Testing of Advanced Digital Networks.

2.2 EXTEST_TRAIN

EXTEST_TRAIN is a mandatory instruction according to the *IEEE 1149.6* [™] *Section 5.4*. It becomes effective at the falling edge of TCK in the UpdateIR TAP controller state. The boundary register is placed between TDI and TDO, similar to the IEEE 1149.1 EXTEST instruction. The timing diagram from the official IEEE 1149.6 document is depicted in Figure 2.

Implementation of IEEE Standard 1149.6TM on QorlQ LS1088A Processor, Rev. 0, 19 May 2022



EXTEST_TRAIN is similar to EXTEST_PULSE except in AC Behavior mode. It enables SerDes TX/TX_B pins to toggle between inverted BSR and non-inverted BSR states for each falling edge of TCK while remaining in the Run-Test/Idle state. This process is shown in the Figure 2 on the AC pin driver signals.

For a thorough description of these instructions, see 1149.6^{TM} -2003, IEEE Standard for Boundary-Scan Testing of Advanced Digital Networks.

3 INIT SETUP instruction

The SerDes channels on the LS1088A are configurable to support the signaling levels required for different interface protocols. To ensure correct electrical behavior, the LS1088A provides the INIT_SETUP instruction and an associated Test Data Register (TDR). These two components allow for the correct configuration of the SerDes pins based on the board configuration where an IEEE 1149.6[™] compliant board interconnect test would be applied.

The INIT_SETUP instruction is a custom public JTAG instruction. It is similar to, yet different from, the INITIALIZE instruction discussed in *IEEE 1149.6*, *ANNEX E*. This instruction is used to preconfigure the electrical parameters of the SerDes RX receivers and TX transmitters to support testing across multiple electrical or physical protocols. Few combinations of signaling levels used by an LS1088A SerDes channel at a given time can potentially be incompatible with SerDes channel signaling of another part on the board. This incompatibility happens due to the difference between the signaling levels of the different protocols. This necessitated the creation of a new instruction to set up the proper voltage levels for the desired protocol during the testing process.

The INIT_SETUP instruction places the TDR between TDI and TDO of the SoC. The proper I/O configuration is shifted-in to set up the correct voltage levels for a given SerDes protocol on a per TX or RX channel basis. Most industrial JTAG board-level interconnect tools support the use of such an instruction to handle multiple physical protocols over a high-speed serial interface.

The INIT_SETUP instruction should be executed as a "preamble" instruction when needed, prior to the execution of other IEEE 1149.1 or IEEE 1149.6 instructions that control the SerDes pins. These instructions are EXTEST, EXTEST_PULSE, EXTEST_TRAIN, and CLAMP. The other IEEE 1149.1-supported instructions (BYPASS, IDCODE, and PRELOAD) always run correctly without the use of the INIT_SETUP instruction.

The SAMPLE instruction is a special case. The INIT_SETUP TDR per-channel settings do not apply during SAMPLE by default, but they are in effect on the TX/TX_B pairs and RX/RX_B pairs if the TDR[sd_sample_override] bit is set. For more information, see the Full TDR layout.

3.1 INIT_SETUP and JTAG TAP state machine

As with prior JTAG implementations, there are two independent sets of controls over the electrical behavior of the SerDes RX and TX analog circuits. The first is the normal, functional "mission" mode, which is how the SerDes lanes are configured in actual production use. The second is JTAG 1149.1/1149.6 test mode where JTAG instructions take priority and control the SerDes RX/TX configurations when the EXTEST instructions are being executed.

Application Note 3 / 39

When INIT_SETUP is the active instruction, the bits of a new TDR are not clocked during the CaptureDR JTAG state. During Shift-DR, the TDR is placed between TDI and TDO of the SoC. The bits shift through the ports of the functional flip-flops of each SerDes lane to load the desired INIT_SETUP data.

NOTE

During the TestLogicReset state or TRST_B assertion, the INIT_SETUP TDR is reset to a default condition (all zeros). The default protocol is PCI Express for SerDes lanes and the SATA-equivalent 200 mV levels for the PLL reference clock lanes, until changed by a subsequent Shift-DR of the INIT_SETUP instruction. There is no action taken during other states of the TAP state machine or during other instructions. When configured, the settings remain undisturbed until either TSRT_B is asserted, the Test Logic Reset State is entered, or the TDR is changed by another Shift-DR of the INIT_SETUP instruction.

3.2 JTAG opcodes

The new IEEE 1149.6[™] JTAG opcodes, as defined in the BSDL file, are shown in Table 1.

Table 1. JTAG 1149.6 public opcodes

JTAG mnemonic	Category	Opcode	
		Binary	Hex
EXTEST_PULSE	Public mandatory	11110101	0xF5
EXTEST_TRAIN		11110110	0xF6
INIT_SETUP	Public custom	11010000	0xD0

3.3 Test Data Register

The TDR is implemented as a serial scan chain. The TDR, described in Table 5, consists of 456 bits. Non-reserved bits contain the bit fields which must configure the platform of SerDes logic for the IEEE 1149.6[™] operation. Reserved bits must be set to 0. Behavior is not guaranteed for non-zero settings of reserved bits. Bit 0 connects to TDO, and bit 405 connects to TDI during INIT_SETUP Shift-DR.

3.3.1 TDR global configuration

The TDR has two global configuration bits that apply to all lanes and five individual control bits for each lane. The global configuration bits are TDR[DDR_vsel_override], TDR[jtag_xpad_lo_volt_sel], and TDR[jtag_sample_override], as follows:

- TDR[DDR_vsel_override] determines the DDR G1VDD voltage level, which is 1.2 V or 1.35 V. See the *LS1088A QorIQ Integrated Processor Hardware Specifications* for the specific voltage ranges.
- TDR[jtag_xpad_lo_volt_sel] is fixed to select SerDes XVDD voltage level to 1.35 V. See the LS1088A QorlQ Integrated Processor Hardware Specifications for the specific voltage ranges.
- TDR[jtag_sample_override] indicates whether explicit protocol control should be employed during the execution of the SAMPLE instruction to override the mission protocol configuration for the purposes of running a test scenario.

Application Note 4 / 39

NOTE

The advanced I/O pins are compliant with the IEEE 1149.6[™] except that there are limitations placed on SAMPLE. These limitations are due to the inherent practical issues associated with capturing the value of gigabit signaling of the slow and asynchronous TCK at the IEEE 1149.6 test receivers across the externally AC-coupled interfaces.

When the TDR[jtag_sample_override] bit is set, the SD1_RXn capture values on the pins during SAMPLE. Unless the value driven is slow or static, the value cannot be predicted. If the lanes are running at a selected protocol frequency, the use of SAMPLE can affect the signal integrity of the functional data transmissions.

When the TDR[jtag_sample_override] bit is set, the SerDes receive and transmit signals using an internal DC-coupled sample configuration based on electrical settings from the TDR register. When the TDR[jtag_sample_override] bit is not set, the SerDes receive and transmit signals using an internal AC-coupled sample configuration based on their normal electrical settings from the functional mission logic during SAMPLE.

An inherent limitation for SAMPLE is that the IEEE 1149.6 test receivers reject high-speed signals as high-frequency 'noise'. Hence, the protocol data rate must be slow enough to pass through this glitch rejection filtering. In addition, it must be fast enough not to decay below the threshold of the test receivers due to the presence of external AC-coupling at the external interface.

3.3.2 TDR SerDes lane protocol configuration

There is a TDR bit field composed of five bits for each lane, shown in the Figure 3. This field is further subdivided into two subfields. The first three bits [4:2] specify the configuration for the RX protocol. The final two bits [1:0] specify the configuration of the TX protocol for the same lane. Fully mapped bit field decode values for configuring the RX and TX protocols are defined in Table 2 and Table 3.

90	89	88	87	86		75	74	73	72	71
SerDes 1 lane A initdata					SerDes	1 lane D	initdata			
	RX		TX		+		RX		Т	X
	IVA			^						

Figure 3. SerDes INIT_SETUP TDR fields for RX and TX

The first three bits specify the decode values for the RX protocol, shown in Table 2.

Table 2. RX configuration protocol decode

RX protocols	INIT_SETUP settings
PEX3, PEX2, PEX, 1000BaseKX	000
Reserved	001
SRIO Short, SGMII 2.5x, QSGMII, JEDEC, SATA, XFI, 10GBaseKR	010
SGMII	011
Reserved	1xx

The final two bits specify the decode values for the TX protocol, shown in Table 3.

Table 3. TX configuration protocol decode

TX protocols	INIT_SETUP settings
PEX3, PEX2, PEX, SGMII 2.5x, HiGig, 10GBaseKR, 1000BaseKX (1.0*full swing)	00
SRIO Short, QSGMII, JEDEC (0.75*full swing)	01

Table continues on the next page...

Application Note 5/39

Table 3. TX configuration protocol decode (continued)

TX protocols	INIT_SETUP settings
SATA, Interlaken 10G, Interlaken Short, JEDEC, XFI (0.585*full swing)	10
SGMII, JDEC (0.667*full swing)	11

The RX and TX settings of a given lane are independent of the settings of all other lanes and also of each other. It is up to the user to program both RX and TX to the same protocol values.

3.3.3 TDR SerDes reference clock configuration

The setting of the configuration bits for the reference clock receivers for SerDes bank is specified in TDR[pll1_config] and TDR[pll2_config] as described in Figure 4 and Table 4.

The final two bits are cleared (set to zero) for the two SerDes reference clock settings because there are no associated TX/TX_B pins.

SerDes bank b							
R	ef Clock	Clea	ared				
Bit 4	Bit 3	Bit 2	0	0			

Figure 4. SerDes INIT_SETUP TDR fields for ref clocks

Table 4 shows the decode values for the reference clocks for SerDes banks.

Table 4. SerDes bank reference clock decode values

Reference clock configuration	INIT_SETUP settings PLL1/2 initdata[4:2]	INIT_SETUP settings PLL1/2 initdata[1:0]
Reference Clock 400 mV min, shunts on-chip AC coupling, used when board is externally AC-Coupled	000	00 Reserved
Reference Clock 200 mV min, shunts on-chip AC coupling, used when board is externally AC-Coupled	010	00 Reserved
Reference Clock 400 mV min, on-chip AC coupling, used when board is externally DC-Coupled	100	00 Reserved
Reference Clock 200 mV min, on-chip AC coupling, used when board is externally DC-Coupled	110	00 Reserved
All other values are reserved	-	00 Reserved

3.3.4 Full TDR layout

It is recommended to use the standard INIT_SETUP instruction before doing any testing in Boundary SCAN. It is mandatory to use INIT_SETUP for any checking of IO pad.

Table 5 lists the format of the entire TDR and the contents of each field.

Table 5. TDR layout

Block	INIT_S ETUP/ TDR Bit	Description	Default		Note
	455	ref_ssp_en	1	Set to 0 for JTAG operations per IP vendor	
	454	ref_clkdiv2	0		
	453		0		
	452		0		
	451		0		
	450	mpll_multiplier	0		
	449	48	0		
	448		0		
	447		0		
	446		1		
	445	tx_vboost_lvl	0	Set to 3'b100 per IP vendor	
USB	444		0		
	443		0		
	442		0		
	441		0		
	440		0		
	439	ssc_ref_clk_sel	0		
	438		0		
	437		0		
	436		0		
	435		0		
	434		0		
	433	ssc_range	0		
	432		0		

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default	Note
	431		0	
	430		0	
	429	acjt_level	0	
	428		0	
	427		0	
	426		0	
	425		0	
	424		0	
	423		0	
	422	pcs_rx_los_mask_val	0	
	421	pcs_ix_ios_iiiask_vai	0	
	420		0	
	419		0	
	418		0	
	417		0	
	416		1	
	415		1	
	414		1	
	413	pcs_tx_swing_full	1	Set to 'd127 per IP vendor
	412		1	
	411		0	
	410		0	
	409		1	
	408	pcs_tx_deemph_6db	0	
	407		0	

9/39

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default	Note
	406		0	
	405		1	
	404		1	
	403		0	
	402		1	
	401	nos ty doomph 2nEdh	1	Sat to 1/1/24 nor ID yandar
	400	pcs_tx_deemph_3p5db	0	Set to 'd24 per IP vendor
	399		0	
	398		0	
	397		1	
	396	los_bias	0	
	395		1	
	394	VATESTENB	0	
	393	VATESTEND	0	
	392	TXPREEMPPULSETUN E	0	
	391		1	
	390	TV/DEETLINEO	0	
	389	TXVREFTUNE0	0	
	388		1	
	387	TXRISETUNE0	0	
	386	TAINIGETUNEU	1	
	385	TXRESTUNE0	0	
	384	IANESTUNEU	1	
	383	TXPREEMPAMPTUNE 0	0	

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default	Note
	382		1	
	381	TXHSXVTUNE0	1	
	380	INFONTONEO	1	
	379		0	
	378	TXFSLSTUNE0	0	
	377	TAPSESTUNEO	1	
	376		1	
	375		0	
	374	SQRXTUNE0	0	
	373		0	
	372		1	
	371	OTGTUNE0	0	
	370		0	
	369		1	
	368	COMPDISTUNE0	0	
	367		0	
	366		0	00 = 3.3 V (do not use)
	365	TVDD Voltage Select	0	01 = 2.5 V 10 = 2.5 V 11 = 1.2 V/1.8 V
Din	364		0	00 = 3.3 V (do not use)
Pin Control	363	LVDD Voltage Select	0	01 = 2.5 V 10 = 2.5 V 11 = 1.2 V/1.8 V
	362		0	00 = 3.3 V
	361	EVDD Voltage Select	0	01 = 2.5 V (do not use) 10 = 2.5 V (do not use)

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default		Note
				11 = 1.2 V/1.8 V	
	360		0	00 = 3.3 V	
	359	DVDD Voltage Select	0	01 = 2.5 V (do not use) 10 = 2.5 V (do not use) 11 = 1.2 V/1.8 V	
	358	Auto-Detect Voltage	0	0 = auto (Voltage Select bits are don't care) 1 = manual (Use Voltage Select bits)	
	357	LVTTL control for ec2_rx_dv	0		
	356	LVTTL control for ec2_rx_clk	0		
	355	LVTTL control for ec2_rxd3	0		
	354	LVTTL control for ec2_rxd2	0		
	353	LVTTL control for ec2_rxd1	0		
	352	LVTTL control for ec2_rxd0	0	0 = LVCMOS input levels	
	351	LVTTL control for ec2_gtx_clk125	0	1 = LVTTL input levels	
	350	LVTTL control for ec2_gtx_clk	0		
	349	LVTTL control for ec2_tx_en	0		
	348	LVTTL control for ec2_txd3	0		
	347	LVTTL control for ec2_txd2	0		

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default
	346	LVTTL control for ec2_txd1	0
	345	LVTTL control for ec2_txd0	0
	344	LVTTL control for ec1_rx_dv	0
	343	LVTTL control for ec1_rx_clk	0
	342	LVTTL control for ec1_rxd3	0
	341	LVTTL control for ec1_rxd2	0
	340	LVTTL control for ec1_rxd1	0
	339	LVTTL control for ec1_rxd0	0
	338	LVTTL control for ec1_gtx_clk125	0
	337	LVTTL control for ec1_gtx_clk	0
	336	LVTTL control for ec1_tx_en	0
	335	LVTTL control for ec1_txd3	0
	334	LVTTL control for ec1_txd2	0
	333	LVTTL control for ec1_txd1	0
	332	LVTTL control for ec1_txd0	0
	331	LVTTL control for usb_pwrfault	0

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default
	330	LVTTL control for usb_drvvbus	0
	329	LVTTL control for iic4_sda	0
	328	LVTTL control for iic4_scl	0
	327	LVTTL control for iic3_sda	0
	326	LVTTL control for iic3_scl	0
	325	LVTTL control for emi_mdio	0
	324	LVTTL control for emi_mdc	0
	323	LVTTL control for irq11	0
	322	LVTTL control for irq10	0
	321	LVTTL control for irq9	0
	320	LVTTL control for irq8	0
	319	LVTTL control for irq7	0
	318	LVTTL control for irq6	0
	317	LVTTL control for irq5	0
	316	LVTTL control for irq4	0
	315	LVTTL control for irq3	0
	314	LVTTL control for sdhc_clk	0
	313	LVTTL control for sdhc_dat3	0
	312	LVTTL control for sdhc_dat2	0

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default
	311	LVTTL control for sdhc_dat1	0
	310	LVTTL control for sdhc_dat0	0
	309	LVTTL control for sdhc_cmd	0
	308	LVTTL control for iic2_sda	0
	307	LVTTL control for iic2_scl	0
	306	LVTTL control for iic1_sda	0
	305	LVTTL control for iic1_scl	0
	304	LVTTL control for uart2_cts_b	0
	303	LVTTL control for uart1_cts_b	0
	302	LVTTL control for uart2_rts_b	0
	301	LVTTL control for uart1_rts_b	0
	300	LVTTL control for uart2_sin	0
	299	LVTTL control for uart1_sin	0
	298	LVTTL control for uart2_sout	0
	297	LVTTL control for uart1_sout	0

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default		Note
	296 295		0	Drive Strength Enable group F, 000 - output driver disabled	
	294	dse_grp_f	0	001 = 240 Ohms 010 = 120 Ohms 011 = 80 Ohms 100 = 60 Ohms 101 = 48 Ohms 110 = 40 Ohms 111 = 34 Ohms (max drive)	Includes pins irq11, irq10, irq9, irq8, irq7, irq6, irq5, irq4, irq3, usb_drvvbus, usb_pwrfault
	293		1	Drive Strength Enable group E,	
	292		1		Includes pins ec1_gtx_clk125,
	291	dse_grp_e	0	001 = 240 Ohms 010 = 120 Ohms 011 = 80 Ohms 100 = 60 Ohms 101 = 48 Ohms 110 = 40 Ohms 111 = 34 Ohms (max drive)	ec1_rx_clk, ec1_rx_dv, ec1_rxd0, ec1_rxd1, ec1_rxd2, ex1_rxd3, ec1_tx_en, ec1_txd0, ec1_txd1, ec1_txd2, ec1_txd3, ec2_gtx_clk, ec2_gtx_clk125, ec2_rx_clk, ec2_rx_dv, ec2_rxd0, ec2_rxd1, ec2_rxd2, ec2_rxd3, ex2_tx_en, ec2_txd0, ec2_txd1, ec2_txd2, ec2_txd3
	290		1	Drive Strength Enable group D,	
	289		1	000 - output driver disabled	
	288	dse_grp_d	1	001 = 240 Ohms 010 = 120 Ohms 011 = 80 Ohms 100 = 60 Ohms 101 = 48 Ohms 110 = 40 Ohms 111 = 34 Ohms (max drive)	Includes pins emi2_mdio

Application Note 15 / 39

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default		Note
	287 286		1	Drive Strength Enable group C, 000 - output driver disabled	
	285	dse_grp_c	1	000 - Output driver disabled 001 = 240 Ohms 010 = 120 Ohms 011 = 80 Ohms 100 = 60 Ohms 101 = 48 Ohms 110 = 40 Ohms 111 = 34 Ohms (max drive)	Includes pins emi2_mdc
	284		1	Drive Strength Enable group B,	
	283		1	000 - output driver disabled	
	282	dse_grp_b	1	001 = 240 Ohms 010 = 120 Ohms 011 = 80 Ohms 100 = 60 Ohms 101 = 48 Ohms 110 = 40 Ohms 111 = 34 Ohms (max drive)	Includes pins sdhc_clk, sdhc_cmd, sdhc_dat0, sdhc_dat1, sdhc_dat2, sdhc_dat3
	281		1	Drive Strength Enable	
	280		0	group A, 000 = output	
	279	dse_grp_a	1	driver disabled 001 = 240 Ohms 010 = 120 Ohms 011 = 80 Ohms 100 = 60 Ohms 101 = 48 Ohms 110 = 40 Ohms 111 = 34 Ohms (max drive)	Includes pins iic1_scl, iic1_sda, iic2_scl, iic2_sda, iic3_scl, iic3_sda, iic4_scl, iic4_sda, uart1_cts_b, uart1_rts_b, uart1_sin, uart1_sout, uart2_cts_b, uart2_rts_b, uart2_sin, uart2_sin, uart2_sout

Application Note 16 / 39

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default	Note
	278	Hysterisis control for ec2_rx_dv	0	
	277	Hysterisis control for ec2_rx_clk	0	
	276	Hysterisis control for ec2_rxd3	0	
	275	Hysterisis control for ec2_rxd2	0	
	274	Hysterisis control for ec2_rxd1	0	
	273	Hysterisis control for ec2_rxd0	0	
	272	Hysterisis control for ec2_gtx_clk125	0	
	271	Hysterisis control for ec2_gtx_clk	0	0=off (CMOS input)
	270	Hysterisis control for ec2_tx_en	0	1= on (Schmitt trigger input)
	269	Hysterisis control for ec2_txd3	0	
	268	Hysterisis control for ec2_txd2	0	
	267	Hysterisis control for ec2_txd1	0	
	266	Hysterisis control for ec2_txd0	0	
	265	Hysterisis control for ec1_rx_dv	0	
	264	Hysterisis control for ec1_rx_clk	0	
	263	Hysterisis control for ec1_rxd3	0	

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default
	262	Hysterisis control for ec1_rxd2	0
	261	Hysterisis control for ec1_rxd1	0
	260	Hysterisis control for ec1_rxd0	0
	259	Hysterisis control for ec1_gtx_clk125	0
	258	Hysterisis control for ec1_gtx_clk	0
	257	Hysterisis control for ec1_tx_en	0
	256	Hysterisis control for ec1_txd3	0
	255	Hysterisis control for ec1_txd2	0
	254	Hysterisis control for ec1_txd1	0
	253	Hysterisis control for ec1_txd0	0
	252	Hysterisis control for usb_pwrfault	0
	251	Hysterisis control for usb_drvvbus	0
	250	Hysterisis control for iic4_sda	0
	249	Hysterisis control for iic4_scl	0
	248	Hysterisis control for iic3_sda	0
	247	Hysterisis control for iic3_scl	0

Application Note 18 / 39

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default
	246	Hysterisis control for emi_mdio	0
	245	Hysterisis control for emi_mdc	0
	244	Hysterisis control for irq11	0
	243	Hysterisis control for irq10	0
	242	Hysterisis control for irq9	0
	241	Hysterisis control for irq8	0
	240	Hysterisis control for irq7	0
	239	Hysterisis control for irq6	0
	238	Hysterisis control for irq5	0
	237	Hysterisis control for irq4	0
	236	Hysterisis control for irq3	0
	235	Hysterisis control for sdhc_clk	0
	234	Hysterisis control for sdhc_dat3	0
	233	Hysterisis control for sdhc_dat2	0
	232	Hysterisis control for sdhc_dat1	0
	231	Hysterisis control for sdhc_dat0	0
	230	Hysterisis control for sdhc_cmd	0
	229	Hysterisis control for iic2_sda	0

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default	Note
	228	Hysterisis control for iic2_scl	0	
	227	Hysterisis control for iic1_sda	0	
	226	Hysterisis control for iic1_scl	0	
	225	Hysterisis control for uart2_cts_b	0	
	224	Hysterisis control for uart1_cts_b	0	
	223	Hysterisis control for uart2_rts_b	0	
	222	Hysterisis control for uart1_rts_b	0	
	221	Hysterisis control for uart2_sin	0	
	220	Hysterisis control for uart1_sin	0	
	219	Hysterisis control for uart2_sout	0	
	218	Hysterisis control for uart1_sout	0	
	217	Slewrate control	1	
	216	for ec2_rx_dv	0	
	215	Slewrate control	1	
	214	for ec2_rx_clk	0	00 = Slow slew rate 01 = Medium slew rate
	213	Slewrate control	1	10 = Fast slew rate
	212	for ec2_rxd3	0	11 = Max slew rate
	211	Slewrate control	1	
	210	for ec2_rxd2	0	

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default
	209	Slewrate control	1
	208	for ec2_rxd1	0
	207	Slewrate control	1
	206	for ec2_rxd0	0
	205	Slewrate control	1
	204	for ec2_gtx_clk125	0
	203	Slewrate control	1
	202	for ec2_gtx_clk	0
	201	Slewrate control	1
	200	for ec2_tx_en	0
	199	Slewrate control	1
	198	for ec2_txd3	0
	197	Slewrate control	1
	196	for ec2_txd2	0
	195	Slewrate control	1
	194	for ec2_txd1	0
	193	Slewrate control	1
	192	for ec2_txd0	0
	191	Slewrate control	1
	190	for ec1_rx_dv	0
	189	Slewrate control	1
	188	for ec1_rx_clk	0
	187		1
	186	Slewrate control for ec1_rxd3	0

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default	
	185	Slewrate control	1	
	184	for ec1_rxd2	0	
	183	Slewrate control	1	
	182	for ec1_rxd1	0	
	181	Slewrate control	1	
	180	for ec1_rxd0	0	
	179	Slewrate control	1	
	178	for ec1_gtx_clk125	0	
	177	Slewrate control	1	
	176	for ec1_gtx_clk	0	
	175	Slewrate control	1	
	174	for ec1_tx_en	0	
	173	Slewrate control	1	
	172	for ec1_txd3	0	
	171	Slewrate control	1	
	170	for ec1_txd2	0	
	169	Slewrate control	1	
	168	for ec1_txd1	0	
	167	Slewrate control	1	
	166	for ec1_txd0	0	
	165	Slewrate control	0	
	164	for usb_pwrfault	0	
	163		0	
	162	Slewrate control for usb_drvvbus	0	

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default
	161	Slewrate control	0
	160	for iic4_sda	0
	159	Slewrate control	0
	158	Slewrate control for iic4_scl	0
	157	Slewrate control	0
	156	for iic3_sda	0
	155	Slewrate control	0
	154	for iic3_scl	0
	153	Slewrate control	1
	152	for emi_mdio	0
	151	Slewrate control	1
	150	for emi_mdc	0
	149		0
	148	Slewrate control for irq11	0
	147		0
	146	Slewrate control for irq10	0
	145		0
	144	Slewrate control for irq9	0
	143		0
	142	Slewrate control for irq8	0
	141		0
	140	Slewrate control for irq7	0
	139		0
	138	Slewrate control for irq6	0
	137	Slewrate control for irq5	0

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default
	136		0
	135	Slewrate control for irq4	0
	134	Slewrate control for irq4	0
	133		0
	132	Slewrate control for irq3	0
	131	Slewrate control	1
	130	for sdhc_clk	0
	129	Slewrate control	1
	128	for sdhc_cmd	0
	127	Slewrate control	1
	126	for sdhc_dat3	0
	125	Slewrate control	1
	124	for sdhc_dat2	0
	123	Slewrate control	1
	122	for sdhc_dat1	0
	121	Slewrate control	1
	120	for sdhc_dat0	0
	119	Slewrate control	0
	118	for iic2_sda	0
	117	Slewrate control	0
	116	for iic2_scl	0
	115	Slewrate control	0
	114	for iic1_sda	0
	113	Slewrate control	0
	112	for iic1_scl	0

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default		Note
	111	Slewrate control	0		
	110	for uart2_cts_b	0		
	109	Slewrate control for uart1_cts_b	0		
	108		0		
	107	Slewrate control for uart2_rts_b Slewrate control for uart1_rts_b	0		
	106		0		
	105		0		
	104		0		
	103	Slewrate control	0		
	102	for uart2_sin	0		
	101	Slewrate control for uart1_sin Slewrate control	0		
	100		0		
	99		0		
	98	for uart2_sout	0		
	97	Slewrate control	0		
	96	for uart1_sout	0		
	95		0	[4] REF Clock ioconfig	111 = Reserved
	94		0	[3] REF Clock ioconfig	110 = Reference Clock 200 mV min, on- chip AC coupling, used when board is externally DC-Coupled
					101 = Reserved
SerDes 1		PLL1 initdata			100 = Reference Clock 400 mV min, on- chip AC coupling, used when board is externally DC-Coupled
	93		0	[2] REF Clock ioconfig	011 = Reserved
					010 = Reference Clock 200 mV min, shunts on-chip AC coupling, used when board is externally AC-Coupled
					001 = Reserved

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default		Note
					000 = Reference Clock 400 mV min, shunts on-chip AC coupling, used when board is externally AC-Coupled
	92		0	[1] reserved	
	91		0	[0] reserved	
	90		0	[4] RX ioconfig	111 = Reserved
	89		0	[3] RX ioconfig	110 = Reserved
				[o] rociocomig	101 = Reserved
					100 = Reserved
					011 = SGMII
	88	Lane A initdata	0	[2] RX ioconfig	010 = SRIO Short, SGMII 2.5x, QSGMII, JEDEC, SATA, XFI, Interlaken Short, Interlaken 10G, 10GBaseKR
					001 = Reserved
					000 = PEX3, PEX2, PEX, 1000BaseKX
	87		0	[1] TX ioconfig	11= SGMII, JDEC (0.667*full swing)
				[0] TX ioconfig	10 = SATA, Interlaken 10G, Interlaken Short, JEDEC, XFI (0.585*full swing) 01 = SRIO Short, QSGMII, JEDEC (0.75*full swing)
	86		0		00 = PEX3, PEX2, PEX, SGMII 2.5x, 10GBaseKR, 1000BaseKX (1.0*full swing)
	85		0	[4] RX ioconfig	111 = Reserved
	84		0	[3] RX ioconfig	110 = Reserved
					101 = Reserved
					100 = Reserved
	Lane B	Lane B initdata			011 = SGMII
			0	[2] RX ioconfig	010 = SRIO Short, SGMII 2.5x, QSGMII, JEDEC, SATA, XFI, Interlaken Short, Interlaken 10G, 10GBaseKR
					001 = Reserved
					000 = PEX3, PEX2, PEX, 1000BaseKX

Application Note 26 / 39

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default		Note
	82		0	[1] TX ioconfig	11= SGMII, JDEC (0.667*full swing)
					10 = SATA, Interlaken 10G, Interlaken Short, JEDEC, XFI (0.585*full swing)
	81		0	[0] TX ioconfig	01 = SRIO Short, QSGMII, JEDEC (0.75*full swing)
					00 = PEX3, PEX2, PEX, SGMII 2.5x, 10GBaseKR, 1000BaseKX (1.0*full swing)
	80		0	[4] RX ioconfig	111 = Reserved
	79		0	[3] RX ioconfig	110 = Reserved
					101 = Reserved
					011 = SGMII
	78	0 Lane C initdata	0	[2] RX ioconfig	010 = SRIO Short, SGMII 2.5x, QSGMII, JEDEC, SATA, XFI, Interlaken Short, Interlaken 10G, 10GBaseKR
					001 = Reserved
					000 = PEX3, PEX2, PEX, 1000BaseKX
	77		0	[1] TX ioconfig	11= SGMII, JDEC (0.667*full swing)
			0		10 = SATA, Interlaken 10G, Interlaken Short, JEDEC, XFI (0.585*full swing)
	76			[0] TX ioconfig	01 = SRIO Short, QSGMII, JEDEC (0.75*full swing)
					00 = PEX3, PEX2, PEX, SGMII 2.5x, 10GBaseKR, 1000BaseKX (1.0*full swing)
	75		0	[4] RX ioconfig	111 = Reserved
	74		0	[3] RX ioconfig	110 = Reserved
		Lane D initdata			101 = Reserved 100 = Reserved
					011 = SGMII
	73		0	[2] RX ioconfig	010 = SRIO Short, SGMII 2.5x, QSGMII, JEDEC, SATA, XFI, Interlaken Short, Interlaken 10G, 10GBaseKR
					001 = Reserved

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default		Note
					000 = PEX3, PEX2, PEX, 1000BaseKX
	72		0	[1] TX ioconfig	11= SGMII, JDEC (0.667*full swing)
					10 = SATA, Interlaken 10G, Interlaken Short, JEDEC, XFI (0.585*full swing)
	71		0	[0] TX ioconfig	01 = SRIO Short, QSGMII, JEDEC (0.75*full swing)
					00 = PEX3, PEX2, PEX, SGMII 2.5x, 10GBaseKR, 1000BaseKX (1.0*full swing)
	70		0	[4] REF Clock ioconfig	111 = Reserved
	69	9 0	[3] REF Clock ioconfig	110 = Reference Clock 200 mV min, on- chip AC coupling, used when board is externally DC-Coupled	
			0	[2] REF Clock ioconfig	101 = Reserved
					100 = Reference Clock 400 mV min, on- chip AC coupling, used when board is externally DC-Coupled
					011 = Reserved
	68	PLL2 initdata			010 = Reference Clock 200 mV min, shunts on-chip AC coupling, used when board is externally AC-Coupled
					001 = Reserved
					000 = Reference Clock 400 mV min, shunts on-chip AC coupling, used when board is externally AC-Coupled
	67		0	[1] reserved	
	66		0	[0] reserved	
	65		0	[4] REF Clock ioconfig	111 = Reserved
	64		0	[3] REF Clock ioconfig	110 = Reference Clock 200 mV min, on- chip AC coupling, used when board is externally DC-Coupled
SerDes 2		PLL1 initdata			101 = Reserved
2	63		0	[2] REF Clock ioconfig	100 = Reference Clock 400 mV min, on- chip AC coupling, used when board is externally DC-Coupled
					011 = Reserved

Application Note 28 / 39

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default		Note
					010 = Reference Clock 200 mV min, shunts on-chip AC coupling, used when board is externally AC-Coupled
					001 = Reserved
					000 = Reference Clock 400 mV min, shunts on-chip AC coupling, used when board is externally AC-Coupled
	62		0	[1] reserved	
	61		0	[0] reserved	
	60		0	[4] RX ioconfig	111 = Reserved
	59		0	[3] RX ioconfig	110 = Reserved
					101 = Reserved
					100 = Reserved
				[2] RX ioconfig	011 = SGMII
	58		0		010 = SRIO Short, SGMII 2.5x, QSGMII, JEDEC, SATA, XFI, Interlaken Short, Interlaken 10G, 10GBaseKR
		Lane A initdata			001 = Reserved
					000 = PEX3, PEX2, PEX, 1000BaseKX
	57		0	[1] TX ioconfig	11= SGMII, JDEC (0.667*full swing)
					10 = SATA, Interlaken 10G, Interlaken Short, JEDEC, XFI (0.585*full swing)
	56		0	[0] TX ioconfig	01 = SRIO Short, QSGMII, JEDEC (0.75*full swing)
					00 = PEX3, PEX2, PEX, SGMII 2.5x, 10GBaseKR, 1000BaseKX
					(1.0*full swing)
	55		0	[4] RX ioconfig	111 = Reserved
	54	Lane B initdata	0	[3] RX ioconfig	110 = Reserved
					101 = Reserved 100 = Reserved
					011 = SGMII
	53		0	[2] RX ioconfig	010 = SRIO Short, SGMII 2.5x, QSGMII, JEDEC, SATA, XFI, Interlaken Short, Interlaken 10G, 10GBaseKR

Implementation of IEEE Standard 1149.6TM on QorlQ LS1088A Processor, Rev. 0, 19 May 2022

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default		Note
					001 = Reserved
					000 = PEX3, PEX2, PEX, 1000BaseKX
	52		0	[1] TX ioconfig	11= SGMII, JDEC (0.667*full swing)
					10 = SATA, Interlaken 10G, Interlaken Short, JEDEC, XFI (0.585*full swing)
	51		0	[0] TX ioconfig	01 = SRIO Short, QSGMII, JEDEC (0.75*full swing)
					00 = PEX3, PEX2, PEX, SGMII 2.5x, 10GBaseKR, 1000BaseKX (1.0*full swing)
	50		0	[4] RX ioconfig	111 = Reserved
	49		0	[3] RX ioconfig	110 = Reserved
					101 = Reserved
			0		100 = Reserved
					011 = SGMII
	48			[2] RX ioconfig	010 = SRIO Short, SGMII 2.5x, QSGMII, JEDEC, SATA, XFI, Interlaken Short, Interlaken 10G, 10GBaseKR
		Lana Cinitelata			001 = Reserved
		Lane C initdata			000 = PEX3, PEX2, PEX, 1000BaseKX
	47		0	[1] TX ioconfig	11= SGMII, JDEC (0.667*full swing)
					10 = SATA, Interlaken 10G, Interlaken Short, JEDEC, XFI (0.585*full swing)
	46		0	[0] TX ioconfig	01 = SRIO Short, QSGMII, JEDEC (0.75*full swing)
					00 = PEX3, PEX2, PEX, SGMII 2.5x, 10GBaseKR, 1000BaseKX (1.0*full swing)
	45		0	[4] RX ioconfig	111 = Reserved
	44	-	0	[3] RX ioconfig	110 = Reserved
		Lane D initdata			101 = Reserved
	43		0	[2] RX ioconfig	100 = Reserved 011 = SGMII

Application Note 30 / 39

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default		Note
					010 = SRIO Short, SGMII 2.5x, QSGMII, JEDEC, SATA, XFI, Interlaken Short, Interlaken 10G, 10GBaseKR
					001 = Reserved
					000 = PEX3, PEX2, PEX, 1000BaseKX
	42		0	[1] TX ioconfig	11= SGMII, JDEC (0.667*full swing)
					10 = SATA, Interlaken 10G, Interlaken Short, JEDEC, XFI (0.585*full swing)
	41		0	[0] TX ioconfig	01 = SRIO Short, QSGMII, JEDEC (0.75*full swing)
					00 = PEX3, PEX2, PEX, SGMII 2.5x, 10GBaseKR, 1000BaseKX (1.0*full swing)
	40		0	[4] REF Clock ioconfig	111 = Reserved
	39		0	[3] REF Clock ioconfig	110 = Reference Clock 200 mV min, on- chip AC coupling, used when board is externally DC-Coupled
					101 = Reserved
					100 = Reference Clock 400 mV min, on- chip AC coupling, used when board is externally DC-Coupled
					011 = Reserved
	38	PLL2 initdata	0	[2] REF Clock ioconfig	010 = Reference Clock 200 mV min, shunts on-chip AC coupling, used when board is externally AC-Coupled
					001 = Reserved
					000 = Reference Clock 400 mV min, shunts on-chip AC coupling, used when board is externally AC-Coupled
	37		0	[1] reserved	
	36		0	[0] reserved	
005	35		0		1
COP	34	ssckio termination	0		
FIG	33		0		

Application Note

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default	Note	
	32		0		
	31	ssckio fixed term/ misc ovrd	0	0 = calibrated, 1 = selected	
	30	ssckio external	0	0 = AC couple, 1 = DC couple	
	29		0	[2]	
	28	ssckio ac_jtag jtag_ctrl threshold value	0	[1]	
	27		0	[0]	
	26	ssckio	0		
	25	to_refclktstx_diff_sysclk	0		
	24	Reserved	0		
	23	Reserved	0		
	22	Reserved	0		
	21	Reserved	0		
	20	SS CKIO Sample Override	0	SS CKIO Sample Override	
	19	SD1 & SD2 Sample Override	0	SD1 & SD2 Sample Override	
	18	Reserved	0		
	17	USB1 PHY reset	0	USB1 PHY reset	
	16	SD2 xvdd_low_vsel	0	0 = 1.5 V, 1 = 1.35 V	
	15	SD1 xvdd_low_vsel	0	0 = 1.5 V, 1 = 1.35 V	
	14		0	[0] 1 = full strength	
	13	DDR_DSE	0	[1] 0 = 1.0 V 1 = 0.9 V	
	12		0	[2]	
	11		0	[3]	

Table 5. TDR layout (continued)

Block	INIT_S ETUP/ TDR Bit	Description	Default		Note
	10		0	[4]	
	9		0	[5]	
	8		0	[6] 1 = mdic cal en	
	7		0	[7] 1 = select mdic cal loop	
	6		0		
	5	DDR TermSel	0		
	4		0		
	3	Reserved	0		
	2	Reserved	0		
	1	Reserved	0		
	0	Global TDR enable	0	For USB and pins_control_dft 0 = Mission control 1 = TDR control	

Table 6 provides USB3.0 RX aio_parametric levels for calculations of S1-S10 levels.

Table 6. USB3.0 ACJTLEVEL[4:0]

Name	ACJTLEVEL[4:0]	AC Mode Vhystedge (+ -)	DC Mode Vhystlevel (+ only)
usb3_v1	00001	94	60
usb3_v2	00010	116	75
usb3_v3	00011	139	90
usb3_v4	00100	162	105
usb3_v5	00101	187	135
usb3_v6	00110	212	150
usb3_v7	10001	185	60
usb3_v8	10010	217	75

3.4 BSDL file

A BSDL file is available for the LS1088A. The full BSDL file is available on the appropriate NXP website.

Application Note 33 / 39

4 IEEE 1149.6 compliant pins

The pins listed in Table 7 are defined as IEEE 1149.6[™] advanced I/O on the LS1088A. All other I/O pins are defined as standard I/O and comply only with the IEEE 1149.1.

Table 7. SerDes pin list

Signal	Signal name	Pin type		
SerDes, PCle, 10GE, 1GE				
SD1_TX0_P	Transmit Data for SerDes Bank 1 Lane A (positive)	0		
SD1_TX1_P	Transmit Data for SerDes Bank 1 Lane B (positive)	0		
SD1_TX2_P	Transmit Data for SerDes Bank 1 Lane C (positive)	0		
SD1_TX3_P	Transmit Data for SerDes Bank 1 Lane D (positive)	0		
SD1_TX0_N	Transmit Data for SerDes Bank 1 Lane A (compliment)	0		
SD1_TX1_N	Transmit Data for SerDes Bank 1 Lane B (compliment)	0		
SD1_TX2_N	Transmit Data for SerDes Bank 1 Lane C (compliment)	0		
SD1_TX3_N	Transmit Data for SerDes Bank 1 Lane D (compliment)	0		
SD1_RX0_P	Receive Data for SerDes Bank 1 Lane A (positive)	1		
SD1_RX1_P	Receive Data for SerDes Bank 1 Lane B (positive)	I		
SD1_RX2_P	Receive Data for SerDes Bank 1 Lane C (positive)	I		
SD1_RX3_P	Receive Data for SerDes Bank 1 Lane D (positive)	1		
SD1_RX0_N	Receive Data for SerDes Bank 1 Lane A (compliment)	1		
SD1_RX1_N	Receive Data for SerDes Bank 1 Lane B (compliment)	1		
SD1_RX2_N	Receive Data for SerDes Bank 1 Lane C (compliment)	I		
SD1_RX3_N	Receive Data for SerDes Bank 1 Lane D (compliment)	I		
SD1_REF_CLK1_P	SerDes Bank 1 PLL 1 Reference Clock (positive)	I		
SD1_REF_CLK2_P	SerDes Bank 1 PLL 2 Reference Clock (positive)	I		
SD1_REF_CLK1_N	SerDes Bank 1 PLL 1 Reference Clock (compliment)	I		
SD1_REF_CLK2_N	SerDes Bank 1 PLL 2 Reference Clock (compliment)	I		
USB1_RX_M	USB PHY SS Receive Data (-)	1		
USB1_RX_P	USB PHY SS Receive Data (+)	1		
USB1_TX_M	USB PHY SS Transmit Data (-)	0		
USB1_TX_P	USB PHY SS Transmit Data (+)	0		
USB2_RX_M	USB PHY SS Receive Data (-)	I		
USB2_RX_P	USB PHY SS Receive Data (+)	I		
USB2_TX_M	USB PHY SS Transmit Data (-)	0		
USB2_TX_P	USB PHY SS Transmit Data (+)	0		

Implementation of IEEE Standard 1149.6TM on QorlQ LS1088A Processor, Rev. 0, 19 May 2022 **Application Note**

4.1 Compliance pins

The compliance pins listed in Table 8 are supported:

Table 8. Compliance pins

Pin	Description	
TBSCAN_EN	TBSCAN_EN_B is an IEEE 1149.1 [™] JTAG compliance enable pin.	
	0: To be compliant to the 1149.1 specification for boundary scan functions. The JTAG-compliant state is documented in the BSDL.	
	1: JTAG connects to DAP controller for the Arm core debug. In normal operation, this pin must be pulled high to OVDD with 4.7 K ohm.	
JTAG_BSR_VSEL	JTAG_BSR_VSEL is an IEEE 1149.1 JTAG compliance enable pin.	
	0: Normal operation. This pin must be pulled down to GND with a pull-down resistor of value 1k ohm.	
	1: To be compliant to the 1149.1 specification for boundary scan functions. The JTAG-compliant state is documented in the BSDL.	
TEST_SEL_B	TEST_SEL_B is an IEEE 1149.1 JTAG compliance enable pin.	
	1: All cores enabled. This pin must be pulled up to OVDD through 1 K resistance.	
	0: Disable core 3 and core 4	
SCAN_MODE_B	SCAN_MODE_B is an IEEE 1149.1 JTAG compliance enable pin.	
	1: Functional mode. This pin must be pulled up to OVDD through 1 K resistance.	
	0: SCAN Mode.	

4.2 Unsupported USB pins

The USB pins listed in Table 9 are not supported in boundary scan:

Table 9. Unsupported USB pins

Pin name	Description	I/O type
USB1_D_M	USB PHY HS data (-)	I/O
USB1_D_P	USB PHY HS data (+)	I/O
USB1_ID	USB PHY ID detect	1
USB1_RESREF	USB PHY impedance calibration	I/O
USB2_D_M	USB PHY HS data (-)	I/O
USB2_D_P	USB PHY HS data (+)	I/O
USB2_ID	USB PHY ID detect	1
USB2_RESREF	USB PHY impedance calibration	I/O

4.3 USB reset counter

The USBPHY requires ~2000 clock cycles to come out of reset before to it can become a part of BSR. A counter inside USB_PHY design uses these 2000 clocks de-asserting reset to internal PHY logic. As long as PHY remains in reset state, the boundary scan

Application Note 35 / 39

continues to fail. Therefore, it is recommended to use INIT_SETUP instructions. The LS1088A device mandates the use of IO config prior to boundary scan.

INIT_SETUP is only 456 bits long and for USB_PHY to come out of reset, ~2000 clock cycles are required. Therefore, to ensure that USB PHY gets required number of cycles to come out of reset, 1906 dummy 0's are shifted through TDI before INIT_SETUP.

5 Revision history

Table 10 summarizes the revisions to this document.

Table 10. Revision history

Revision	Date	Description
0	19 May 2022	Initial public release

Implementation of IEEE Standard 1149.6TM on QorlQ LS1088A Processor, Rev. 0, 19 May 2022

Application Note 36 / 39

Legal information

Definitions

Draft — A draft status on a document indicates that the content is still under internal review and subject to formal approval, which may result in modifications or additions. NXP Semiconductors does not give any representations or warranties as to the accuracy or completeness of information included in a draft version of a document and shall have no liability for the consequences of use of such information.

Disclaimers

Limited warranty and liability — Information in this document is believed to be accurate and reliable. However, NXP Semiconductors does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information. NXP Semiconductors takes no responsibility for the content in this document if provided by an information source outside of NXP Semiconductors.

In no event shall NXP Semiconductors be liable for any indirect, incidental, punitive, special or consequential damages (including - without limitation - lost profits, lost savings, business interruption, costs related to the removal or replacement of any products or rework charges) whether or not such damages are based on tort (including negligence), warranty, breach of contract or any other legal theory.

Notwithstanding any damages that customer might incur for any reason whatsoever, NXP Semiconductors' aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the Terms and conditions of commercial sale of NXP Semiconductors.

Right to make changes — NXP Semiconductors reserves the right to make changes to information published in this document, including without limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

Suitability for use — NXP Semiconductors products are not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or equipment, nor in applications where failure or malfunction of an NXP Semiconductors product can reasonably be expected to result in personal injury, death or severe property or environmental damage. NXP Semiconductors and its suppliers accept no liability for inclusion and/or use of NXP Semiconductors products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.

Applications — Applications that are described herein for any of these products are for illustrative purposes only. NXP Semiconductors makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification.

Customers are responsible for the design and operation of their applications and products using NXP Semiconductors products, and NXP Semiconductors accepts no liability for any assistance with applications or customer product design. It is customer's sole responsibility to determine whether the NXP Semiconductors product is suitable and fit for the customer's applications and products planned, as well as for the planned application and use of customer's third party customer(s). Customers should provide appropriate design and operating safeguards to minimize the risks associated with their applications and products.

NXP Semiconductors does not accept any liability related to any default, damage, costs or problem which is based on any weakness or default in the customer's applications or products, or the application or use by customer's third party customer(s). Customer is responsible for doing all necessary testing for the customer's applications and products using NXP Semiconductors products in order to avoid a default of the applications and the products or of the application or use by customer's third party customer(s). NXP does not accept any liability in this respect.

Terms and conditions of commercial sale — NXP Semiconductors products are sold subject to the general terms and conditions of commercial sale, as published at http://www.nxp.com/profile/terms, unless otherwise agreed in a valid written individual agreement. In case an individual agreement is concluded only the terms and conditions of the respective agreement shall apply. NXP Semiconductors hereby expressly objects to applying the customer's general terms and conditions with regard to the purchase of NXP Semiconductors products by customer.

Export control — This document as well as the item(s) described herein may be subject to export control regulations. Export might require a prior authorization from competent authorities.

Suitability for use in non-automotive qualified products — Unless this data sheet expressly states that this specific NXP Semiconductors product is automotive qualified, the product is not suitable for automotive use. It is neither qualified nor tested in accordance with automotive testing or application requirements. NXP Semiconductors accepts no liability for inclusion and/or use of non-automotive qualified products in automotive equipment or applications.

In the event that customer uses the product for design-in and use in automotive applications to automotive specifications and standards, customer (a) shall use the product without NXP Semiconductors' warranty of the product for such automotive applications, use and specifications, and (b) whenever customer uses the product for automotive applications beyond NXP Semiconductors' specifications such use shall be solely at customer's own risk, and (c) customer fully indemnifies NXP Semiconductors for any liability, damages or failed product claims resulting from customer design and use of the product for automotive applications beyond NXP Semiconductors' standard warranty and NXP Semiconductors' product specifications.

Application Note 37/39

Translations — A non-English (translated) version of a document, including the legal information in that document, is for reference only. The English version shall prevail in case of any discrepancy between the translated and English versions.

Security — Customer understands that all NXP products may be subject to unidentified vulnerabilities or may support established security standards or specifications with known limitations. Customer is responsible for the design and operation of its applications and products throughout their lifecycles to reduce the effect of these vulnerabilities on customer's applications and products. Customer's responsibility also extends to other open and/or proprietary technologies supported by NXP products for use in customer's applications. NXP accepts no liability for any vulnerability. Customer should regularly check security updates from NXP and follow up appropriately.

Customer shall select products with security features that best meet rules, regulations, and standards of the intended application and make the ultimate design decisions regarding its products and is solely responsible for compliance with all legal, regulatory, and security related requirements concerning its products, regardless of any information or support that may be provided by NXP.

NXP has a Product Security Incident Response Team (PSIRT) (reachable at PSIRT@nxp.com) that manages the investigation, reporting, and solution release to security vulnerabilities of NXP products.

Trademarks

Notice: All referenced brands, product names, service names, and trademarks are the property of their respective owners.

NXP — wordmark and logo are trademarks of NXP B.V.

AMBA, Arm, Arm7, Arm7TDMI, Arm9, Arm11, Artisan, big.LITTLE, Cordio, CoreLink, CoreSight, Cortex, DesignStart, DynamlQ, Jazelle, Keil, Mali, Mbed, Mbed Enabled, NEON, POP, RealView, SecurCore, Socrates, Thumb, TrustZone, ULINK, ULINK2, ULINK-ME, ULINK-PLUS, ULINKpro, µVision, Versatile — are trademarks or registered trademarks of Arm Limited (or its subsidiaries) in the US and/or elsewhere. The related technology may be protected by any or all of patents, copyrights, designs and trade secrets. All

Airfast — is a trademark of NXP B.V.

rights reserved.

Bluetooth — the Bluetooth wordmark and logos are registered trademarks owned by Bluetooth SIG, Inc. and any use of such marks by NXP Semiconductors is under license.

Cadence — the Cadence logo, and the other Cadence marks found at www.cadence.com/go/trademarks are trademarks or registered trademarks of Cadence Design Systems, Inc. All rights reserved worldwide.

CodeWarrior — is a trademark of NXP B.V.

ColdFire — is a trademark of NXP B.V.

ColdFire+ - is a trademark of NXP B.V.

EdgeLock — is a trademark of NXP B.V.

EdgeScale — is a trademark of NXP B.V.

EdgeVerse — is a trademark of NXP B.V.

eIQ — is a trademark of NXP B.V.

FeliCa — is a trademark of Sony Corporation.

Freescale — is a trademark of NXP B.V.

HITAG — is a trademark of NXP B.V.

ICODE and I-CODE — are trademarks of NXP B.V.

Immersiv3D — is a trademark of NXP B.V.

12C-bus — logo is a trademark of NXP B.V.

Kinetis — is a trademark of NXP B.V.

Layerscape — is a trademark of NXP B.V.

Mantis — is a trademark of NXP B.V.

MIFARE — is a trademark of NXP B.V.

MOBILEGT - is a trademark of NXP B.V.

NTAG — is a trademark of NXP B.V.

Processor Expert — is a trademark of NXP B.V.

QorlQ — is a trademark of NXP B.V.

SafeAssure — is a trademark of NXP B.V.

SafeAssure — logo is a trademark of NXP B.V.

StarCore — is a trademark of NXP B.V.

Synopsys — Portions Copyright © 2021 Synopsys, Inc. Used with permission. All rights reserved.

Tower — is a trademark of NXP B.V.

UCODE — is a trademark of NXP B.V.

VortiQa — is a trademark of NXP B.V.

Application Note 38 / 39



Please be aware that important notices concerning this document and the product(s) described herein, have been included in section 'Legal information'.

© NXP B.V. 2022.

All rights reserved.

For more information, please visit: http://www.nxp.com
For sales office addresses, please send an email to: salesaddresses@nxp.com

Date of release: 19 May 2022 Document identifier: AN5384